

4-2-14 ch 27 continued (rest 3 review)

also: ch 28 (later)

ch 27 so far we covered: FORCE ON MOVING CHARGE (see #8, → 3-31-14 notes) and on a wire with NON-ZERO current.

$$(A) \vec{F} = q \vec{v} \times \vec{B}$$

$$(B) \vec{F} (\text{on wire}) = I \vec{L} \times \vec{B}$$

\vec{L} (in meters) points along I and $|\vec{L}| =$ wire segment length

section 27.3

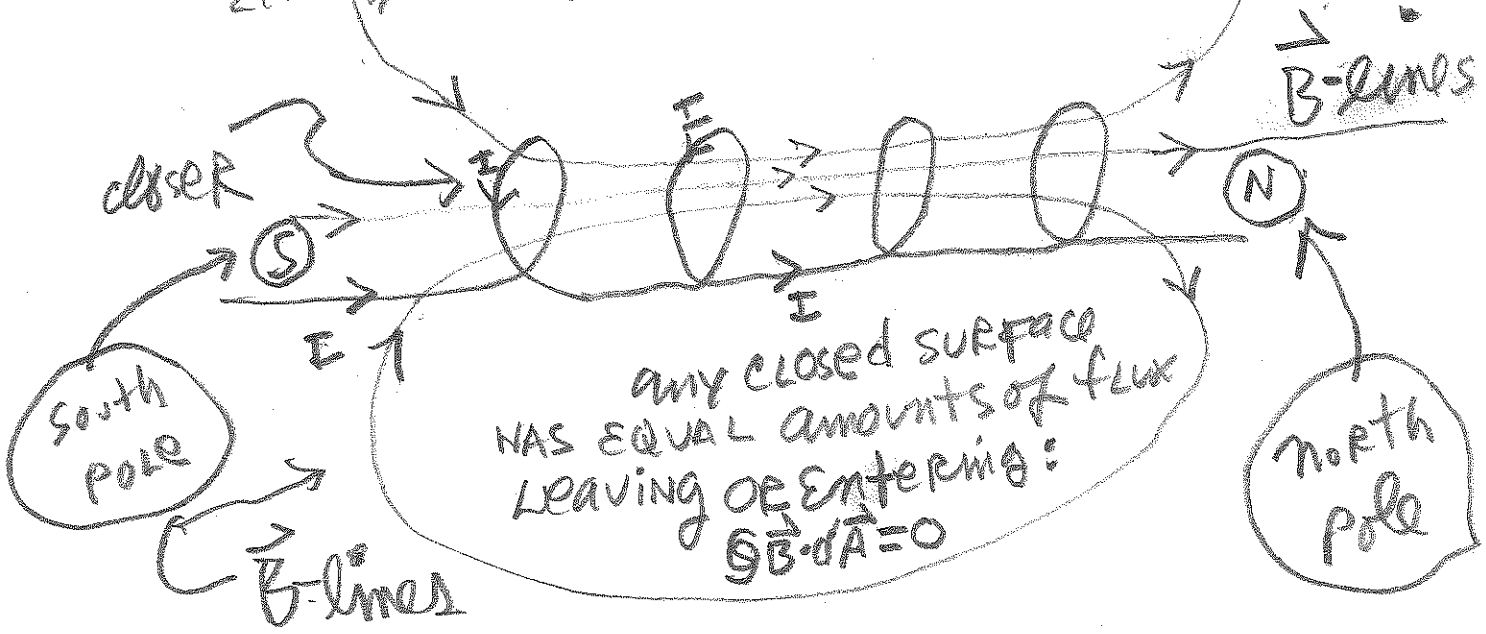
G.S. = "Gaussian" closed SURFACE

$\oint_{G.S.} \vec{B} \cdot d\vec{A} = 0$

NO MAGNETIC CHARGE INSIDE

NOTE: \vec{B} is in loops; NO START OR END.

example: lab on solenoid:

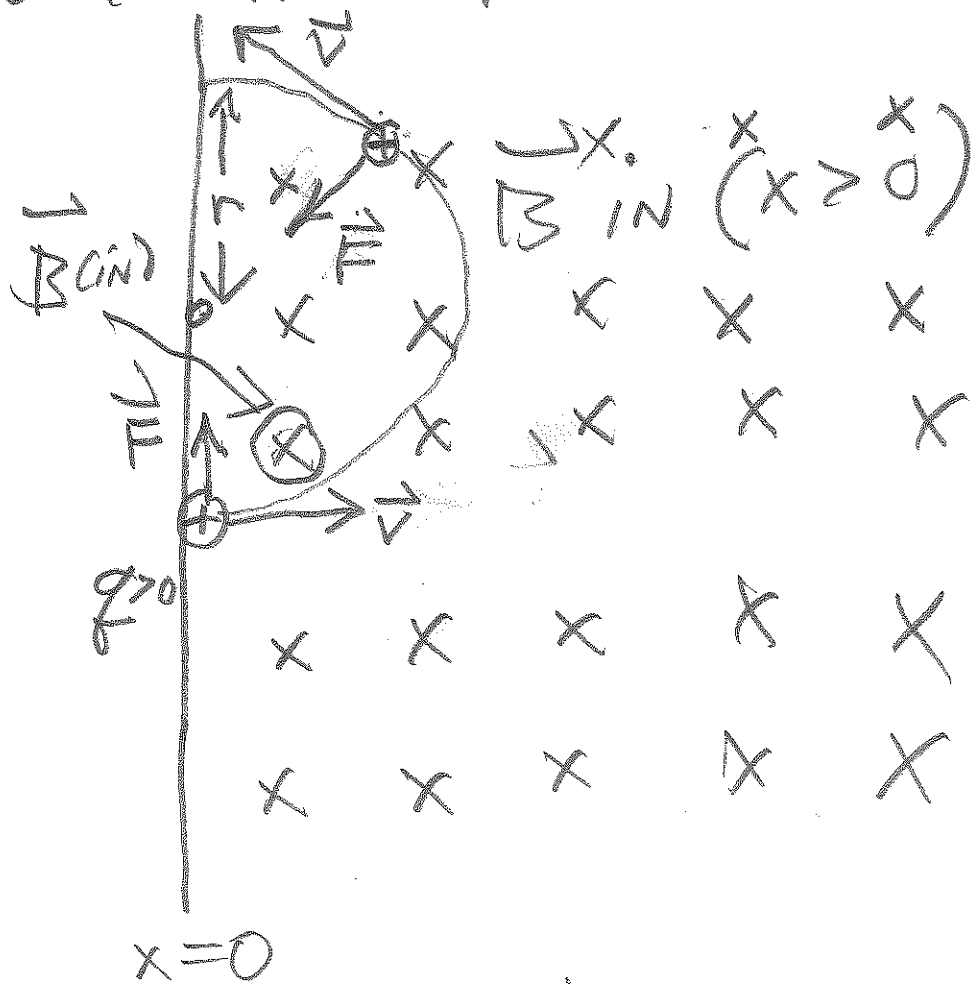


Section 27.4

motion in a circle: application
is a MASS spectrometer.

see
Fig 27.17

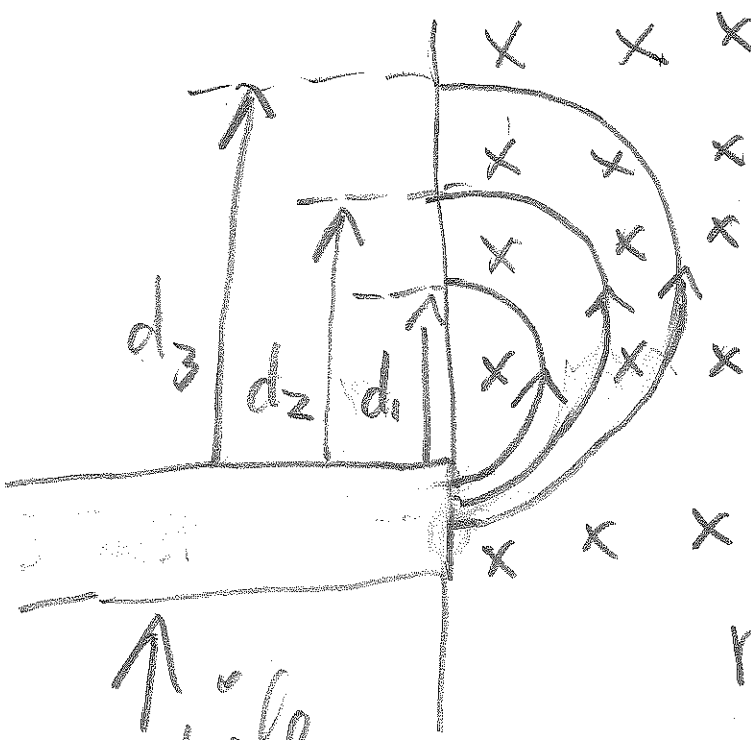
$\vec{B} = 0$
($x < 0$)



$$F = |\vec{F}| = |q\vec{v} \times \vec{B}| = qv \cdot B \sin 90^\circ = qvB$$

$$\text{BUT ALSO, } F = \frac{mv^2}{r} \Rightarrow \frac{mv^2}{r} = qvB$$

$$\rightarrow r = \frac{m v}{q B}$$



$$\left. \begin{aligned} d_1 &= 2r_1 \\ d_2 &= 2r_2 \\ d_3 &= 3r_3 \end{aligned} \right\} m_1 < m_2 < m_3$$

$$r_i = \frac{m_i v}{q B}$$

$$\Delta r = \frac{\Delta m v}{q B} \rightarrow \Delta m = \frac{q B \Delta r}{v}$$

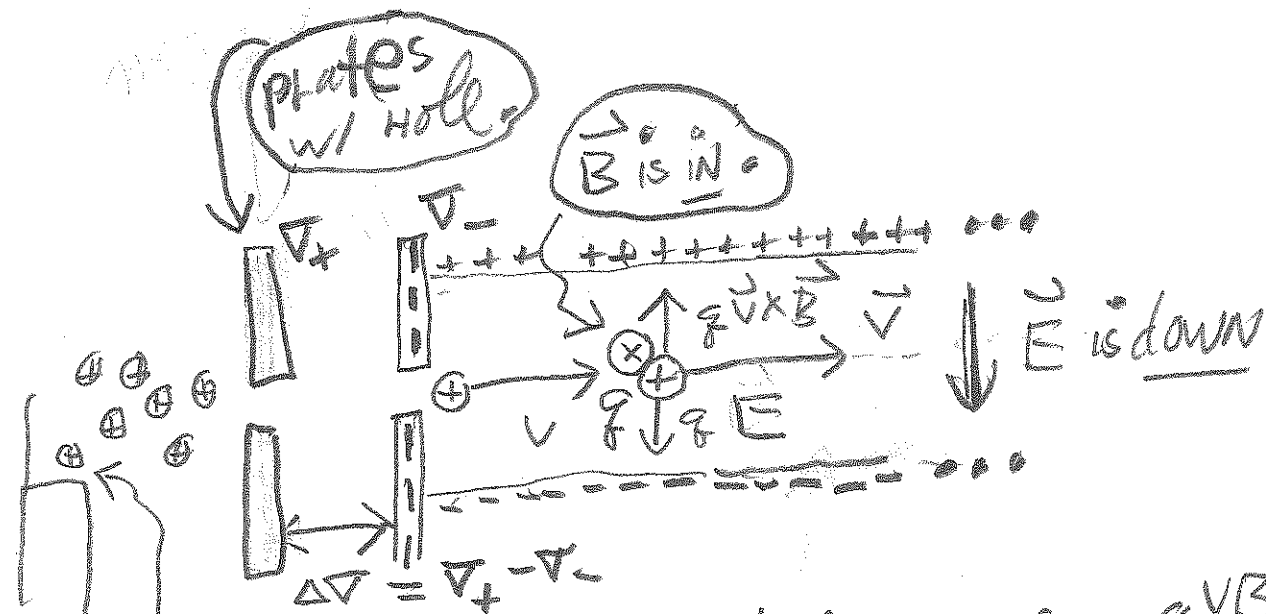
↑ Particle beam with various masses, same charge.

[CRUDE MASS SPECTROMETER]

Sec 27.5 motion applications:

High energy physics to study fundamental laws; EARLY QUANTUM FOUNDATION (1919)
 see Fig 27.22:

- velocity selector used to measure e/m ; below let $q=e$ until LAST STEP.



source of charged particles

$$\text{net force} = 0 = qvB - qE$$

$$\Rightarrow v = \frac{E}{B}, \text{ where } E = \frac{\Delta V}{d}$$

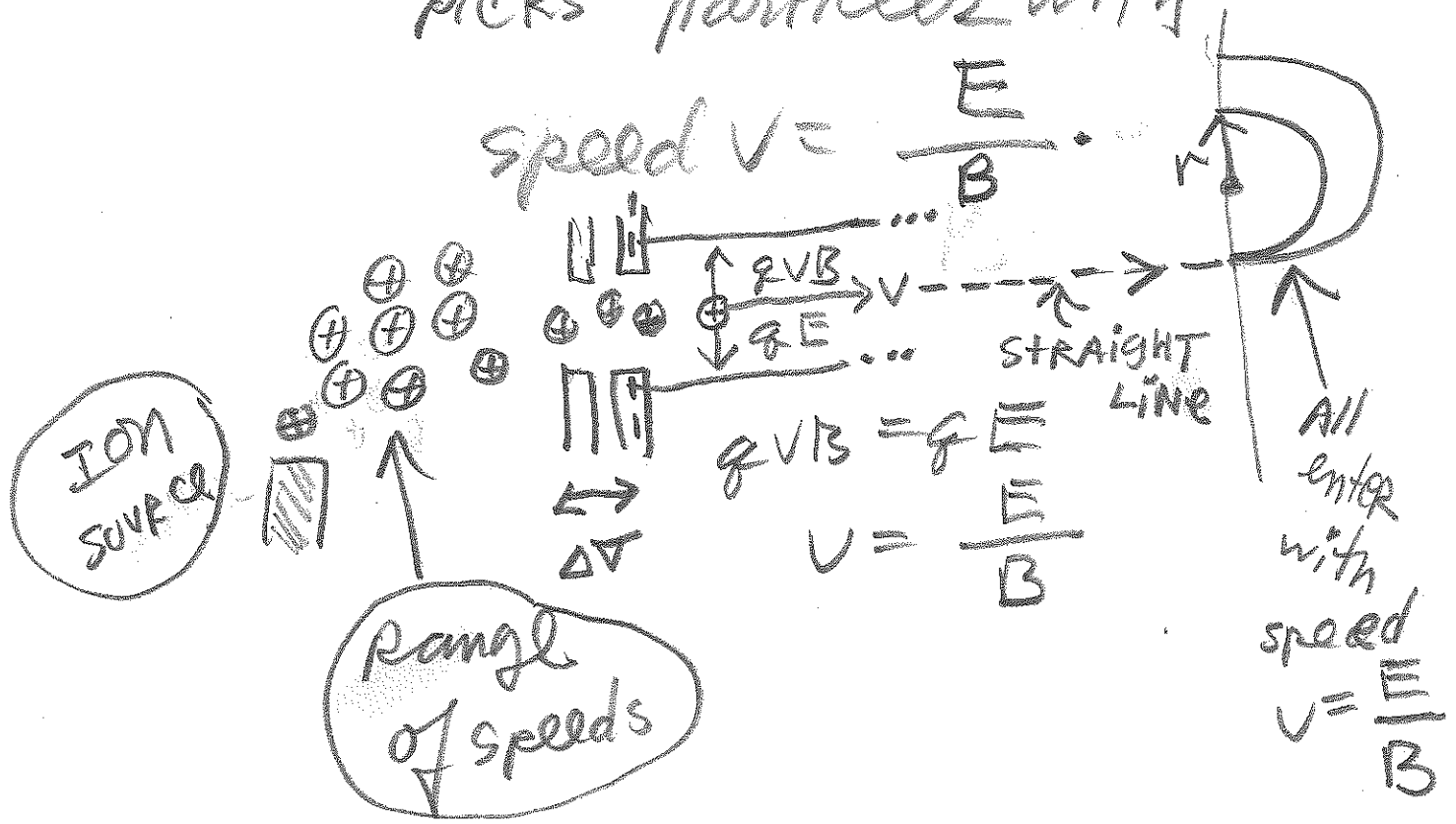
$$\frac{1}{2}mv^2 = q\Delta V \Rightarrow v = \sqrt{\frac{2 \cdot \Delta V \cdot q}{m}}$$

$$v = \frac{E}{B} = \sqrt{\frac{2q\Delta V}{m}} \Rightarrow \frac{e}{m} = \frac{E^2}{2\Delta V B^2}$$

MASS SPECTROMETER

Range of speeds;
velocity selector
picks particles with

$$\text{speed } v = \frac{E}{B}$$

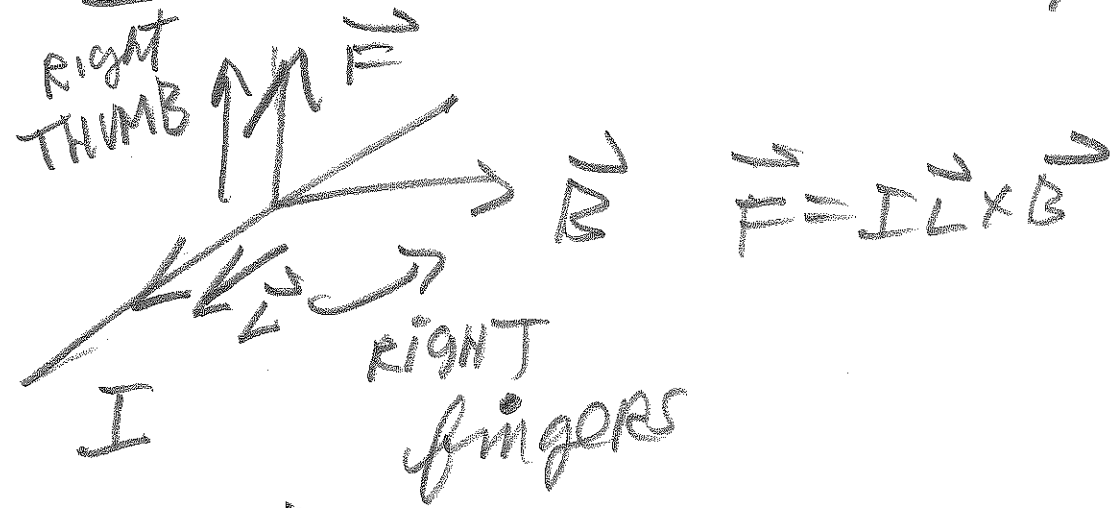


From before: $r = \frac{mv}{qB}$

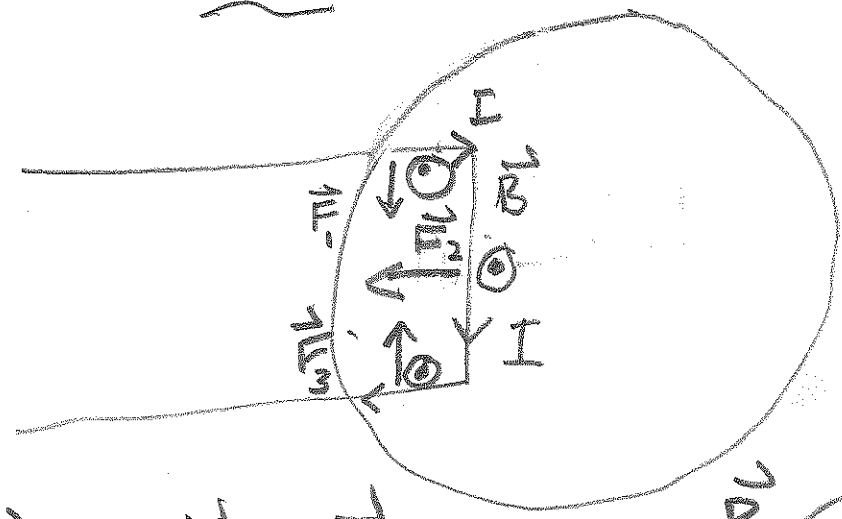
$$\Delta r = \frac{\Delta mv}{qB}$$

$$\Delta m = \frac{qB \Delta r}{v}$$

Sec 27.6 discussed already.



QUIZ
25, ch 27:

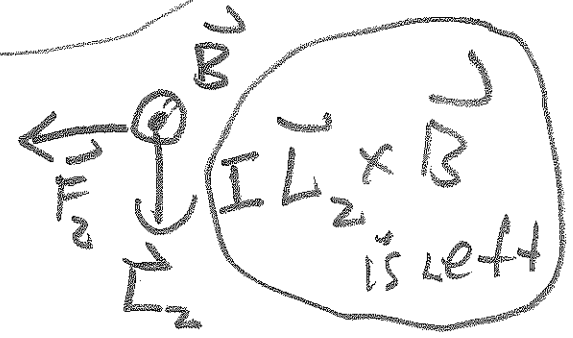


$$\vec{F}_2 = I\vec{L}_2 \times \vec{B}$$

$$\vec{F}_1 + \vec{F}_3 = 0$$

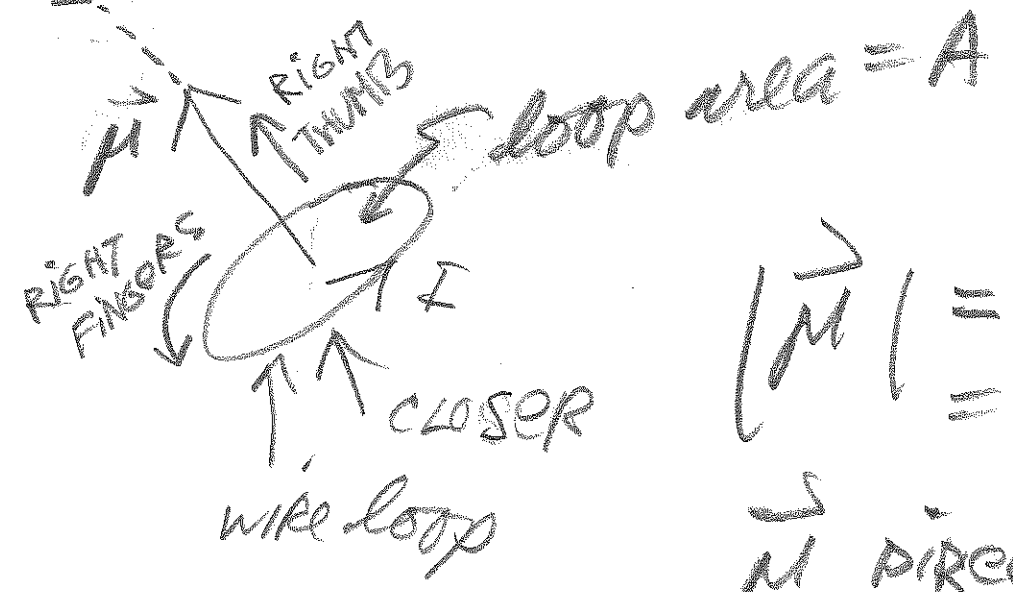
$$|\vec{F}_2| = IL_2 B \sin 90$$

$$= IL_2 B$$



4B 4-2-17 supplement

eye \downarrow fig 27.31 \bullet μ direction and magnitude.

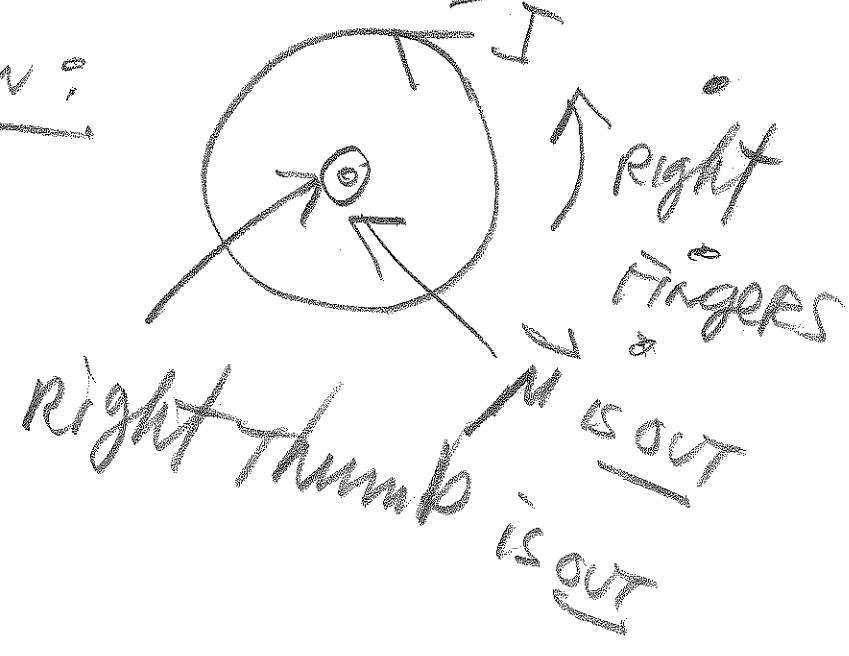


$$|\vec{M}| = I \cdot \text{area}$$

$$= I \cdot A$$

\vec{M} DIRECTION FROM RIGHT HAND RULE.

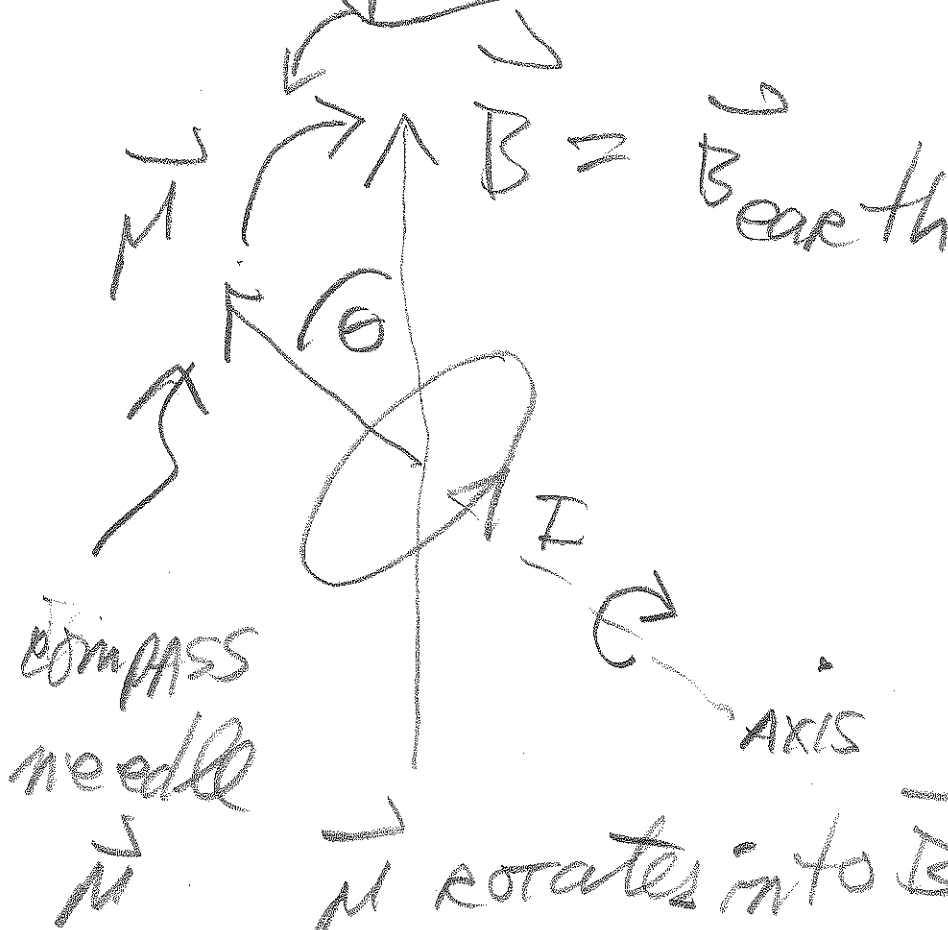
eye view:



(2)

\vec{M} ROTATES INTO \vec{B}

ASSOCIATED TORQUE
 $= \vec{M} \times \vec{B}$



\vec{M} ROTATES INTO \vec{B} DUE TO
a TORQUE GIVEN BY

$$\tau = |\vec{\tau}| = |\vec{M}| \cdot |\vec{B}| \sin \theta$$

$\tau = MB \sin \theta$ MAGNITUDE

Big APPLICATION: EVERYDAY COMPASS.