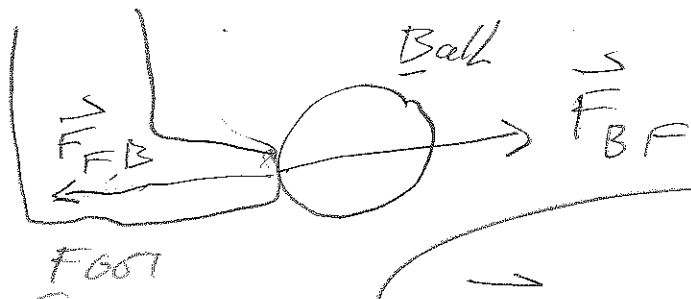


3RD  
LAW  
CH 4

Review: Between 2 Bodies

FOR EVERY ACTION THERE IS A REACTION

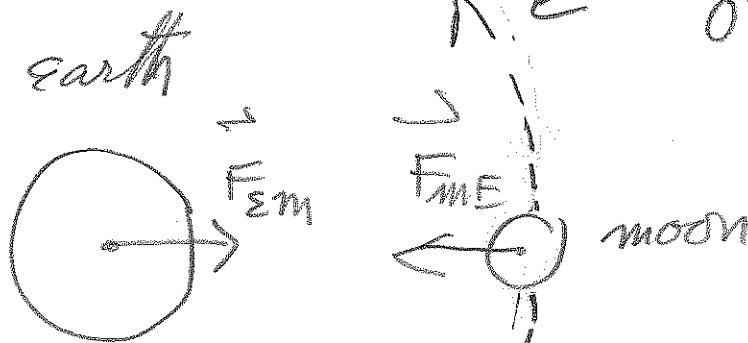
FIG 4.25



$$\vec{F}_{FB} = -\vec{F}_{BF}$$

NOTE:  
USE 2ND  
LAW  
TO GET  
a of BALL =  
 $\vec{a} = \frac{\vec{F}_{BF}}{m_B}$

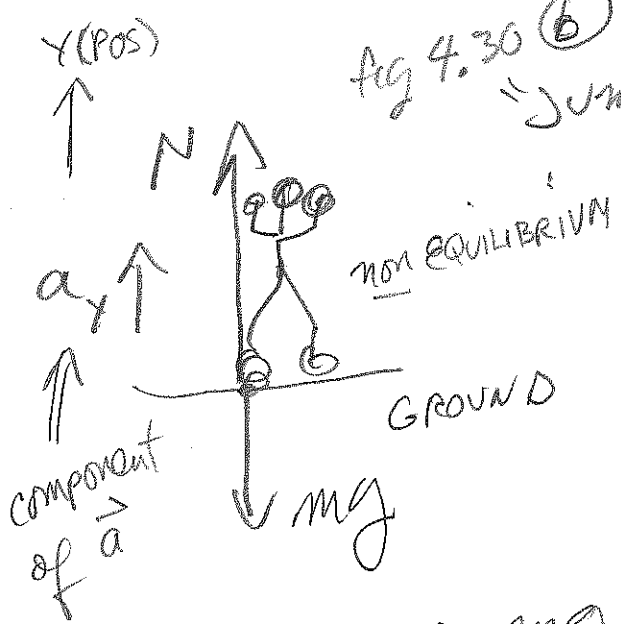
MY EXAMPLE



$$\vec{F}_{ME} = -\vec{F}_{EM}$$

CIRCULAR  
ORBIT.

Fig 4.30 (b) "Jump up"



$$N = N_{PG} > mg$$

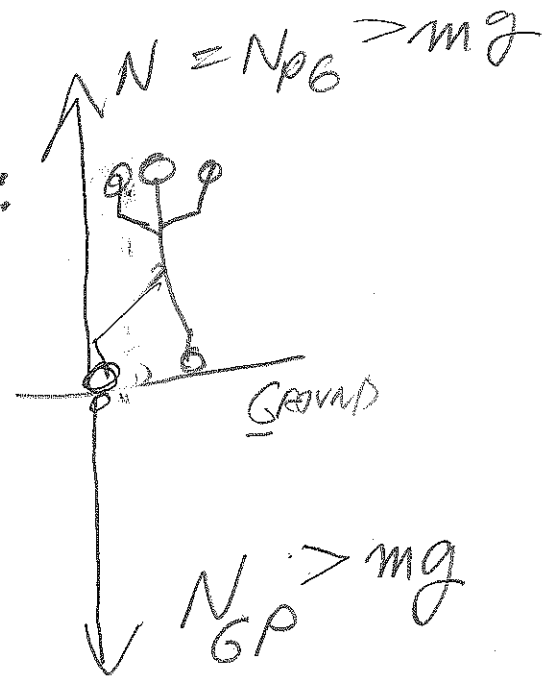
net force

y (pos)  
↑

$$\Sigma F_y = \text{pos} - \text{neg}$$

$$ma_y = N_{PG} - mg$$

NOT 4:

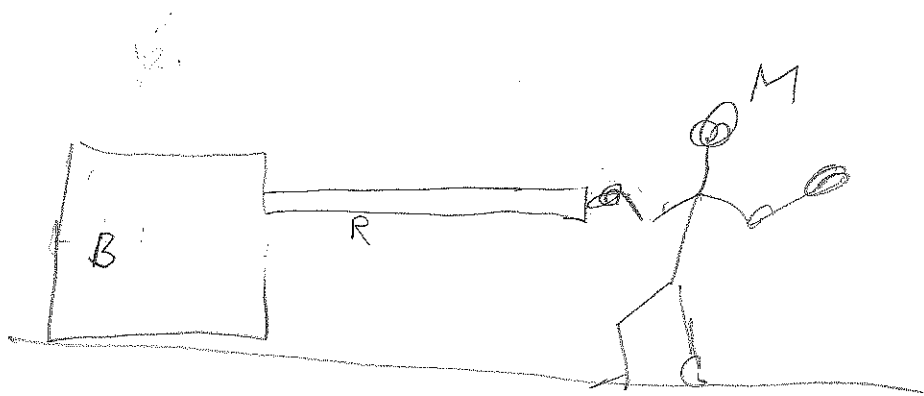


$$\vec{N}_{PG} = -\vec{N}_{GP}$$

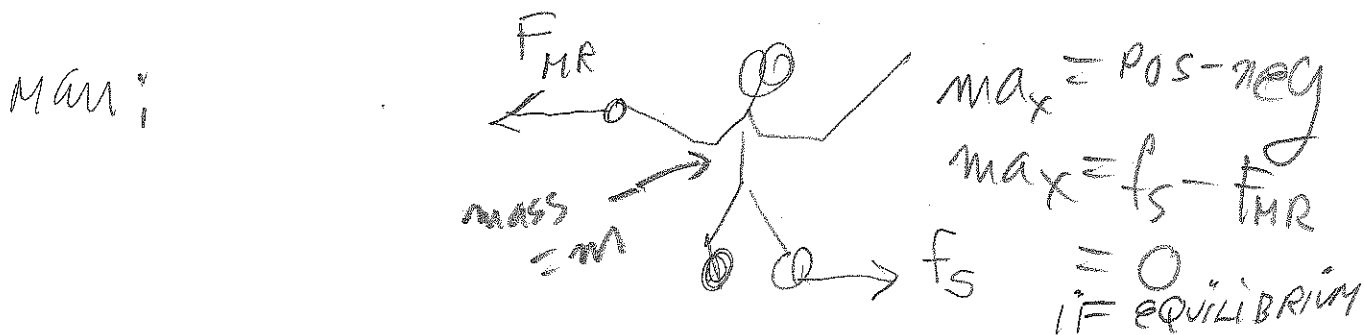
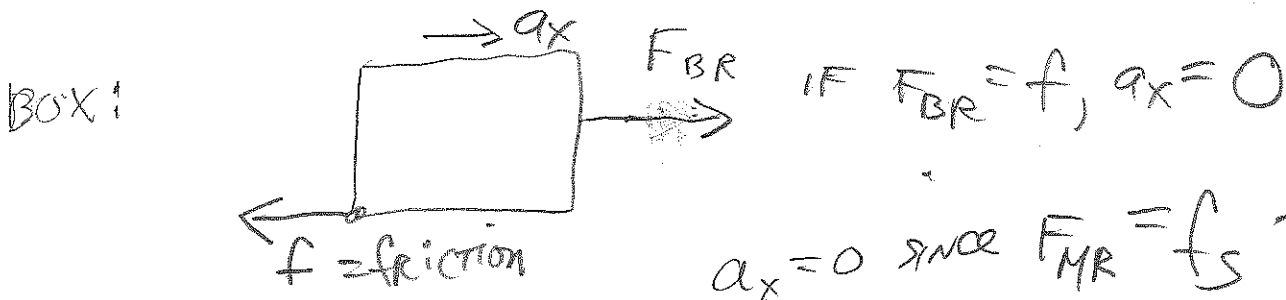
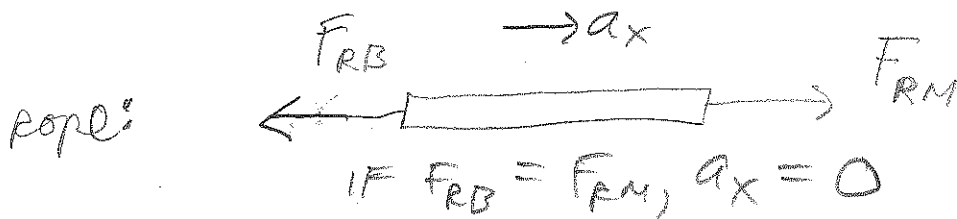
CH 4-5 as a unit of thought

Newton's 3rd LAW

Example 7.10



Isolate



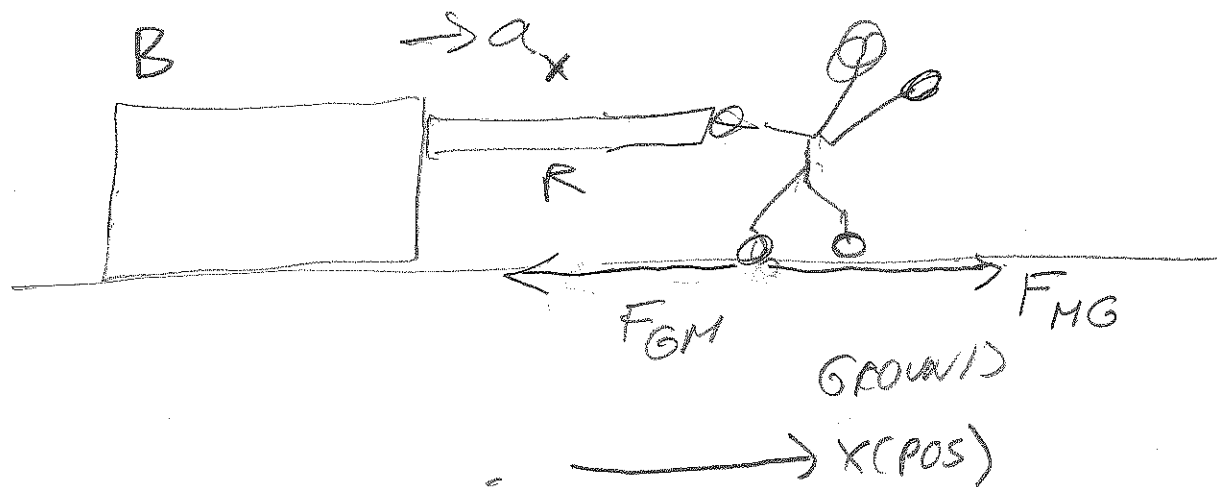
Example 4.10

$$F_{RM} = F_{MR}$$

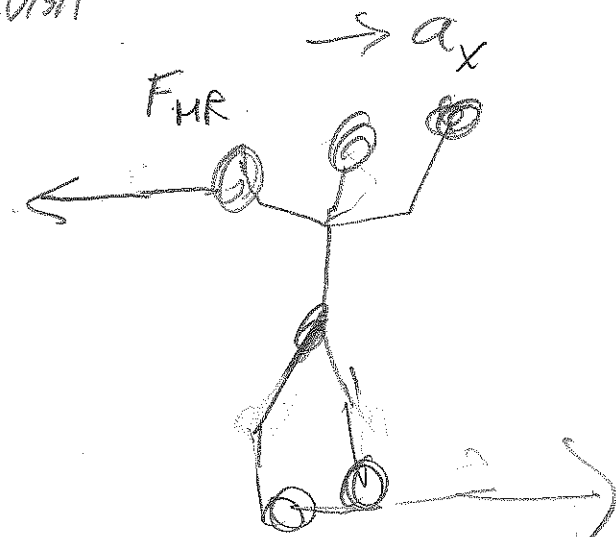
$$F_{BR} = F_{RB}$$

Equal  
magnitudes  
(3RD LAW)

NOTE walking and pulling  
ROPE + BOX

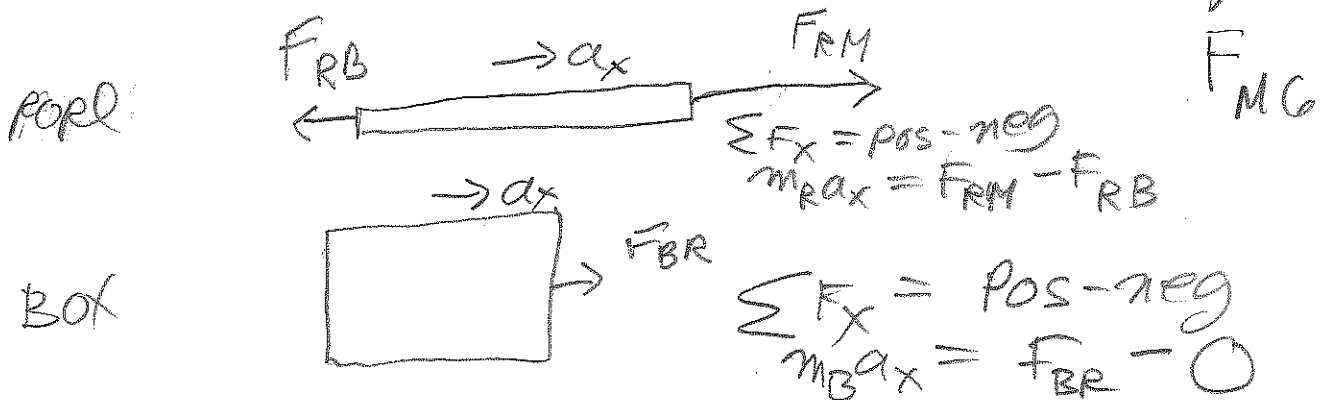


now revisit



$$\Sigma F_x = \text{pos} - \text{neg}$$

$$m_M a_x = F_{MG} - F_{MR}$$



3 EQUATIONS

$$\textcircled{\text{I}} \quad m_M a_x = F_{MG} - F_{MR}$$

$$\textcircled{\text{II}} \quad m_R a_x = F_{RM} - F_{RB}$$

$$\textcircled{\text{III}} \quad m_B a_x = F_{BR}$$

note  $F_{MR} = F_{RM}$  and  $F_{RB} = F_{BR}$   
from 3RD LAW NEWTON

ADD 3 EQUATIONS TO CANCEL  $F_{MR}$  and  $F_{RB}$   
WHERE  $F_{MR} = F_{RM}$  and  $F_{RB} = F_{BR}$

$$\text{ADP: } m_M a_x + m_R a_x + m_B a_x = F_{MG}$$

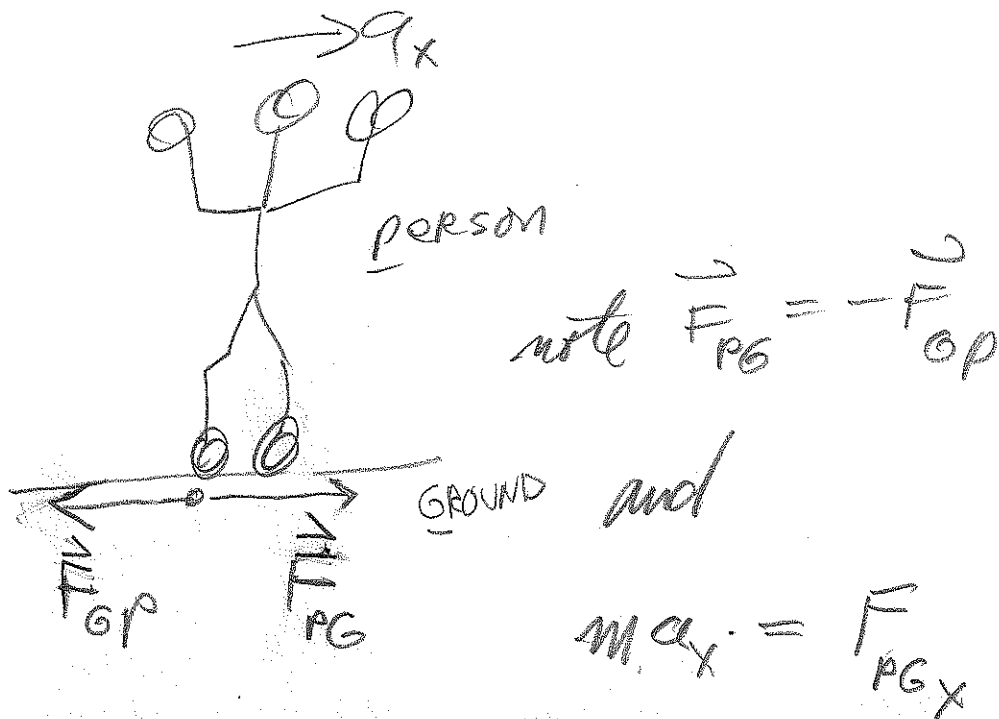
$$\Rightarrow a_x = \frac{F_{MG}}{m_M + m_R + m_B}$$

WHERE  $\vec{F}_{MG}$  = REACTION FORCE OF  
GROUND ON M

# Example 4.9

# see page 125 Review

fig 4.30(a) explains walking

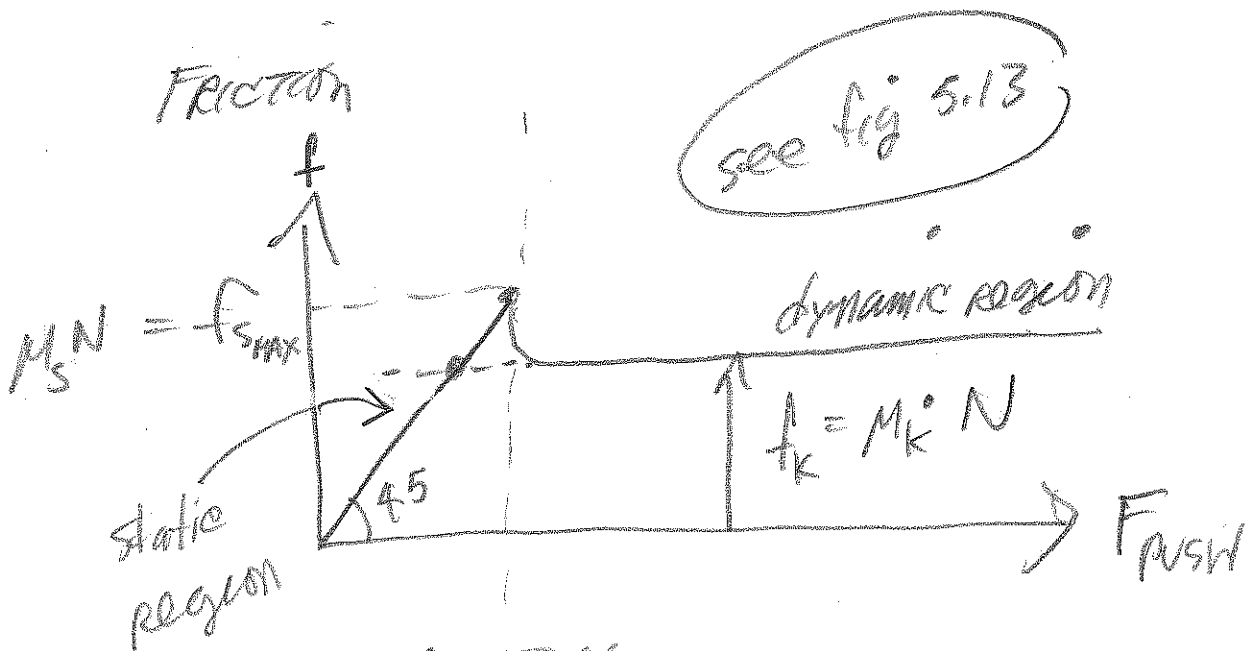


CH 5 All examples

\* at rest

$\vec{a} = 0$	{	Example 5.4 ✓	* <u>Static EQUILIBRIUM</u>	** MOVING
		Example 5.5	** <u>DYNAMIC EQUILIBRIUM</u>	
		Example 5.6	NON-EQUILIBRIUM	
		5.7		
		5.8		
		5.9		
		(T=0) 5.10 ✓		
		5.11		
		5.12		

}  $\vec{a} \neq 0$

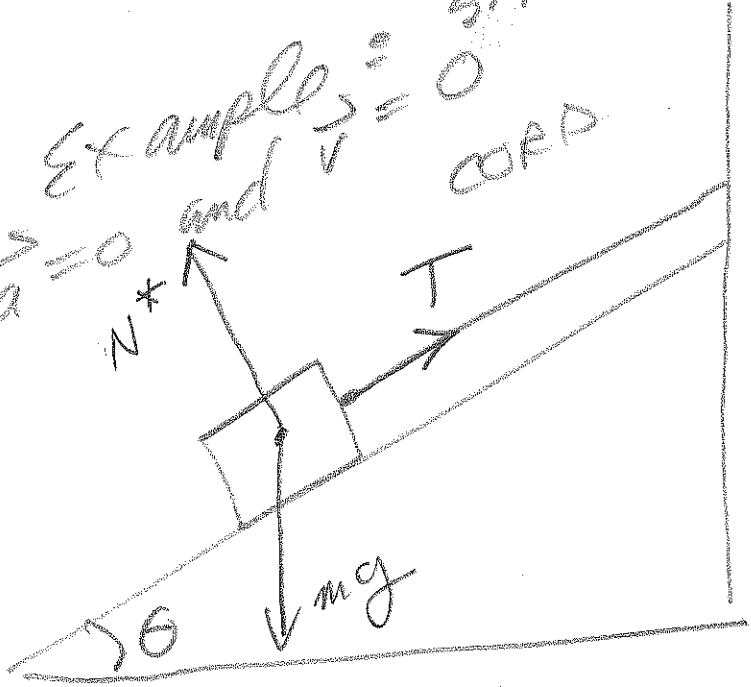


Example 5.16

Example 5.17 ✓



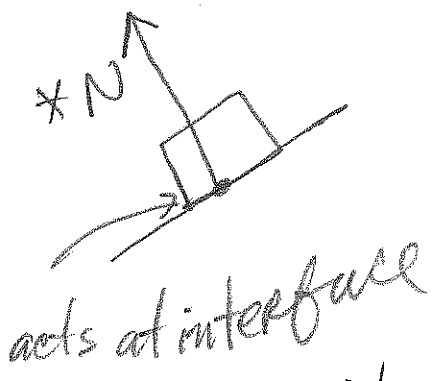
Example:  $\vec{a} = 0$  and  $\vec{v} = 0$   
 COORD



$$T = |\vec{T}|$$

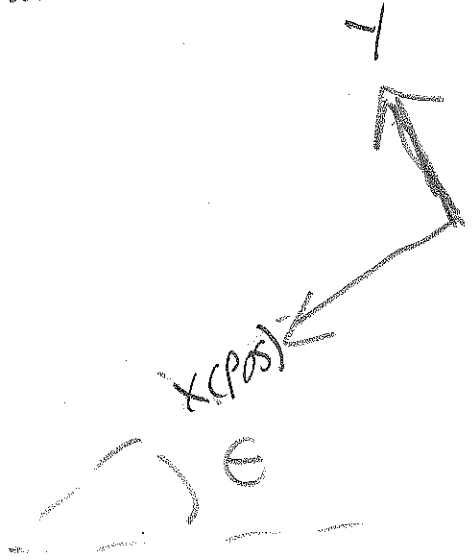
$$N = |\vec{N}|$$

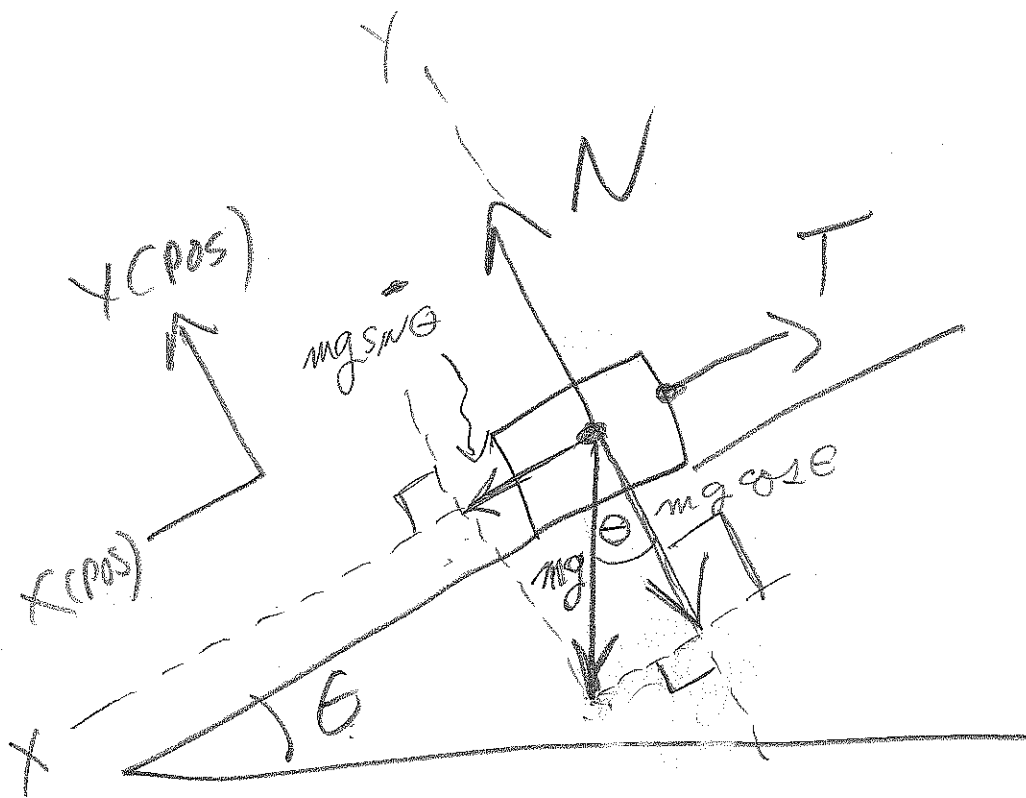
$$mg = |mg|$$



(A) CHOOSE X ALONG  
 incline (see test #1,  
 #5)

(B) DECOMPOSE  
 EACH VECTOR  
 ALONG x AND y





$$\Sigma F_x = \text{pos} - \text{neg}$$

$$m a_x = m g \sin \theta - T$$

EQUILIBRIUM  $\circ = m g \sin \theta - T$

$$a_x = 0$$

$$T = m g \sin \theta \quad \text{SPECIAL CASE}$$

$$\Sigma F_y = \text{pos} - \text{neg}$$

$$m a_y = N - m g \cos \theta$$

SINCE

$$\circ = N - m g \cos \theta$$

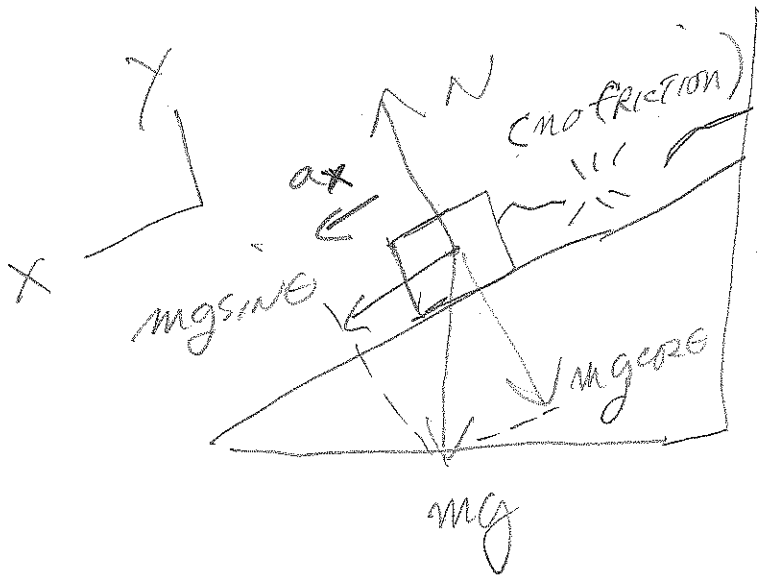
$a_y = 0$   
(EQUILIBRIUM)

$$N = m g \cos \theta$$

GENERALLY TRUE

cut the cable ( $T=0$ )

$\Rightarrow$  cut to example 5.10



$$\Sigma F_x = \text{POS} - \text{NEG}$$

$$ma_x = mg \sin \theta - 0$$

$$a_x = g \sin \theta \leq g$$

$$\text{SINCE } \sin \theta \leq 1$$

Galileo  
lab  
( $5^\circ < \theta < 10^\circ$ )

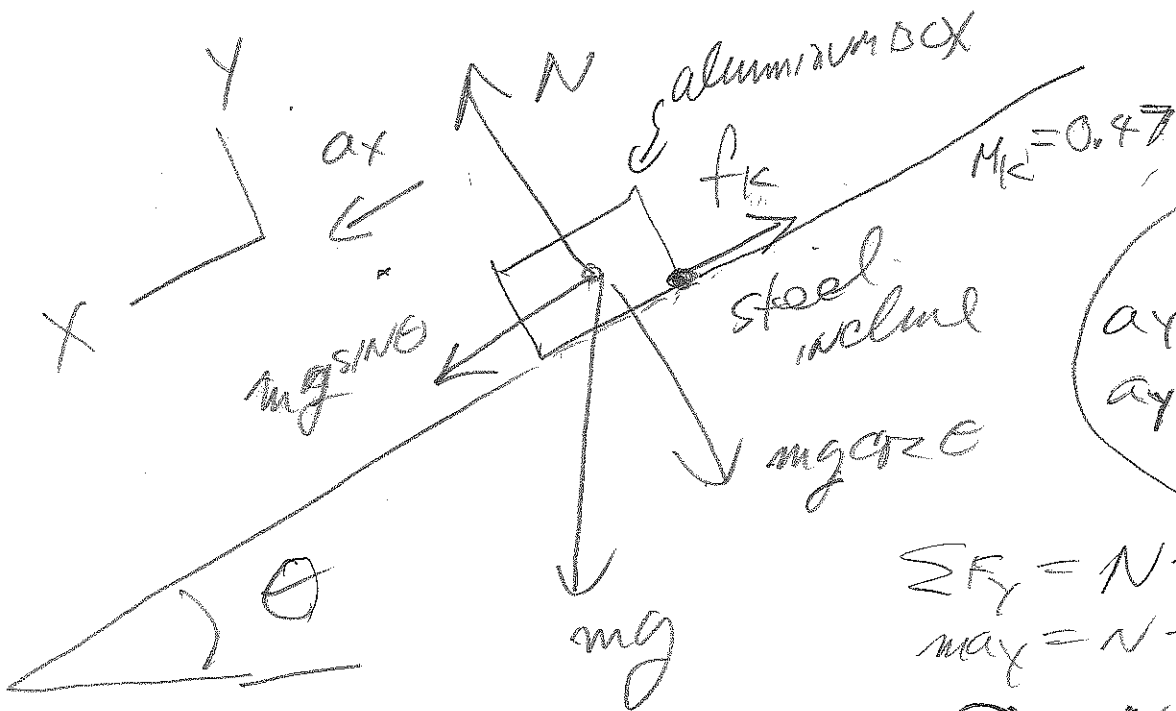
Example 3.17 ( $\mu_k$  is given)

use  $f_k = \mu_k \cdot N$

Table of coefficients (pg 147 table 5.1)

Examples al on steel ( $\mu_k = 0.47$ )

Rubber on concrete ( $\mu_k = 0.8$ )



$a_y = \frac{dy}{dt} = 0$   
 $a_y = 0$  since  $v_y = 0$   
 $v_y = \text{constant}$

$\Sigma F_y = N - mg \cos \theta$   
 $ma_y = N - mg \cos \theta$

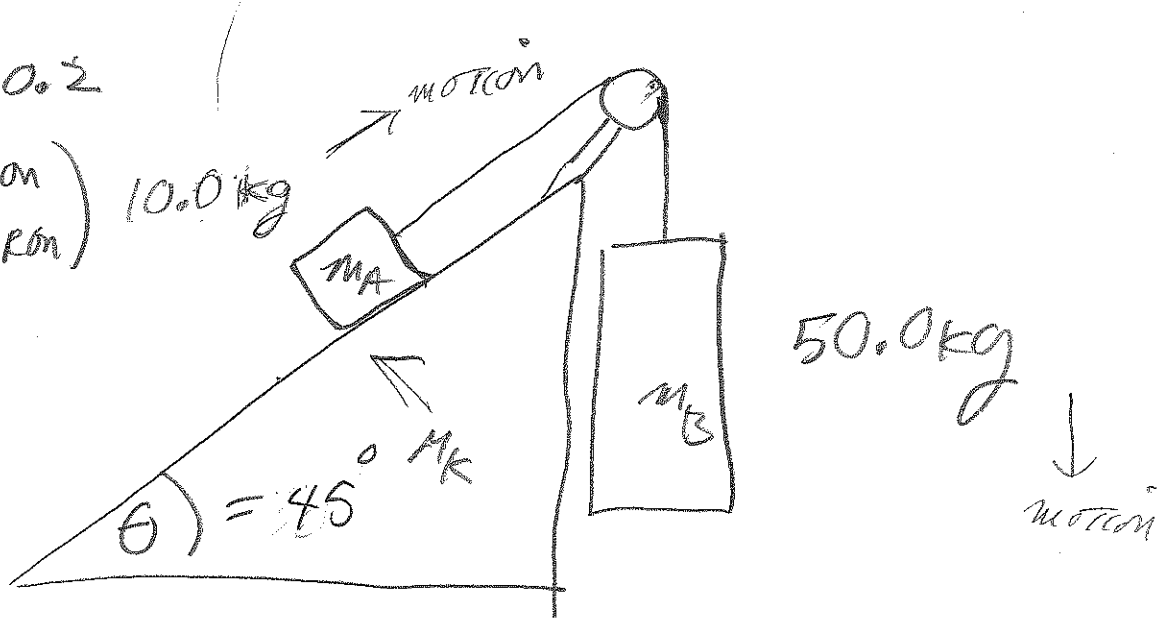
$0 = N - mg \cos \theta$   
 $N = mg \cos \theta$   
 $f_k = \mu_k N$

$\Sigma F_x = \text{pos - neg}$   
 $ma_x = mg \sin \theta - f_k$

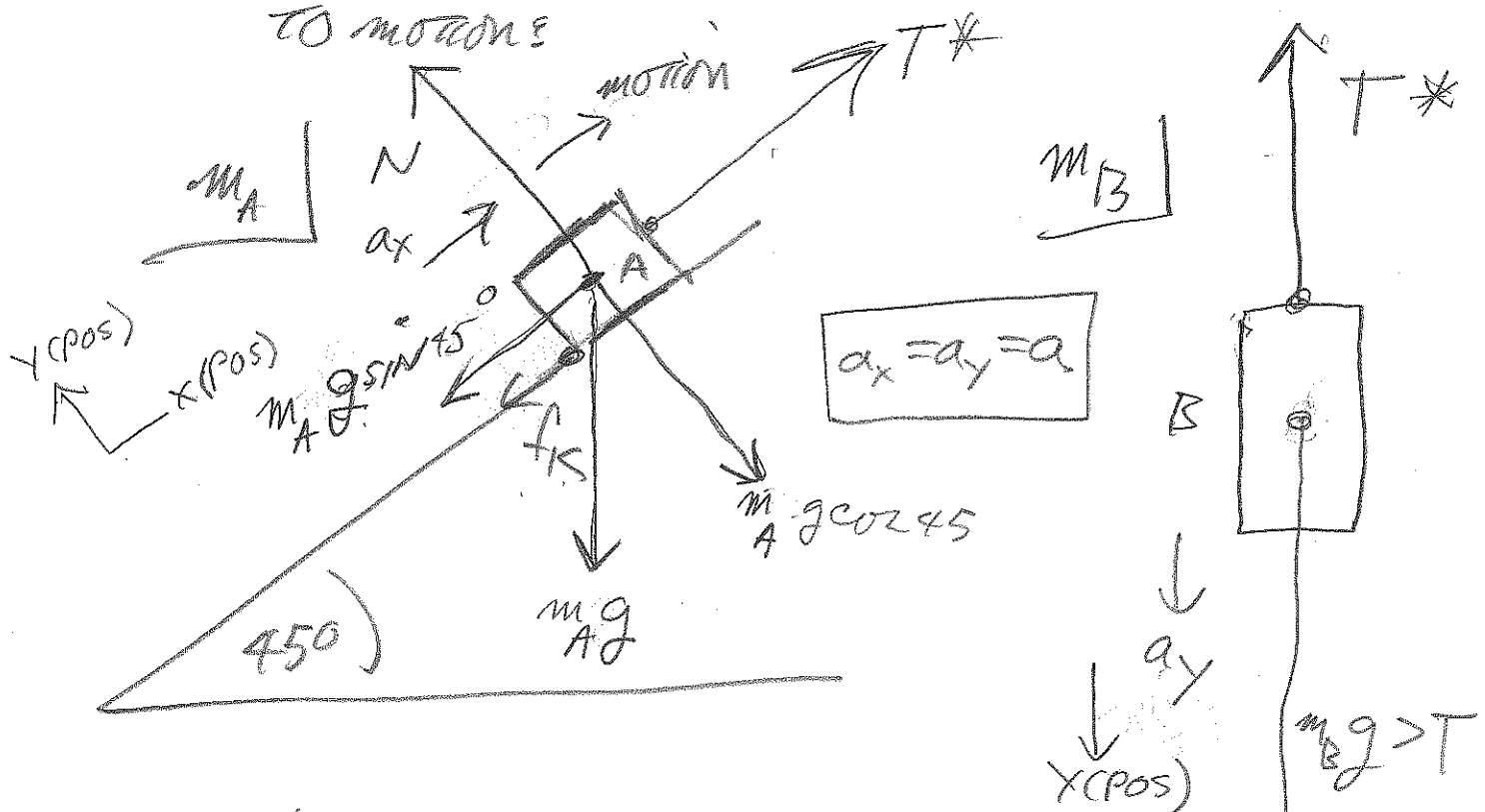
$ma_x = mg \sin \theta - \mu_k mg \cos \theta \Rightarrow a_x = g \sin \theta - \mu_k g \cos \theta$

# SUMMARY problem

$M_k = 0.2$   
(ZINC ON  
CAST IRON)

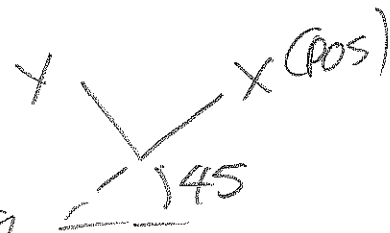


Isolate objects; PICK AXES according TO MOTIONS



$T^*$  same  $T$ 's since string is massless and PULLEY is also massless.

$m_A$



$$m_A a_x = \text{pos} - \text{neg}$$

$$m_A a_x = T - m_A g \sin 45 - f_k$$

note:  $\sum F_y = m_A a_y = 0 = N_A - m_A g \cos 45$

$$N_A = m_A g \cos 45$$

$$m_A a_x = T - m_A g \sin 45 - \mu_k m_A g \cos 45$$

$m_B$



$$m_B a_y = \text{pos} - \text{neg}$$

$$m_B a_y = m_B g - T$$

$$a_y = a_x = a$$

UNKNOWNSE  
a and T

(I)  $m_A a = T - m_A g \sin 45 - \mu_k m_A g \cos 45$

(II)  $m_B a = m_B g - T$

ADD  $m_A a + m_B a = m_B g - m_A g \sin 45 - \mu_k m_A g \cos 45$

$$a = \frac{m_B g - m_A g \sin 45 - \mu_k m_A g \cos 45}{(m_A + m_B)}$$

$$a \approx \frac{416 \text{ (N)}}{60 \text{ kg}}$$

$$a = \boxed{6.93 \text{ m/s}^2}$$

$$a = 7 \frac{\text{m}}{\text{s}^2}$$