

10-18-13

Test 2 Oct 30. WED

11

2A

CH 3



PROJECTILE

Relative

CIRCULAR MOTION

CH 4

newton's LAWS

CH 5

*CH 6 circular dynamics

CH 7

conservation of energy
with KE and U_g only.

$$KE_i + mgy_i = KE_f + mgy_f$$

$$(KE = \frac{1}{2}mv^2)$$

$$KE_i = \frac{1}{2}mv_i^2$$

$$KE_f = \frac{1}{2}mv_f^2$$

NO friction: see # see #48, 87* - CH 7

ALSO #49, #45, #46 (CH 7)

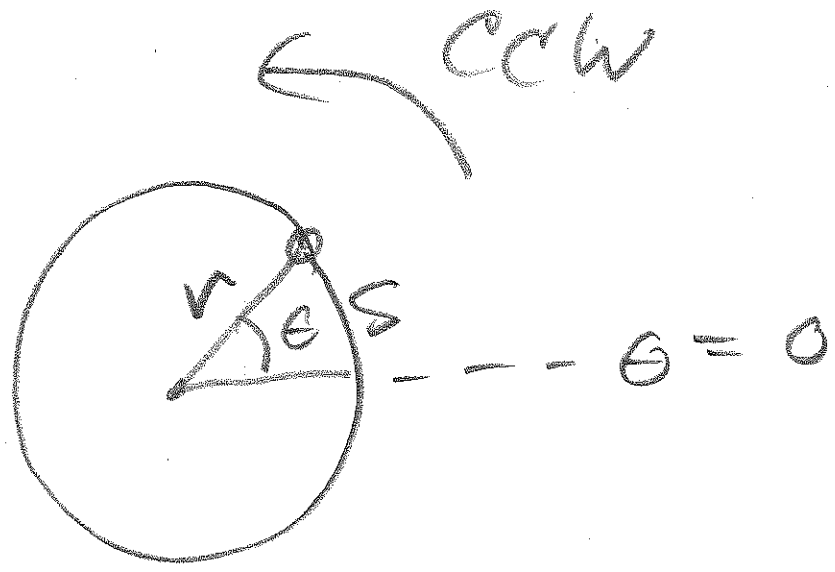
See All

PROBLEMS I WORKED

OUT. NOTE *87, CH 7 INVOLVES CH 6.

CH 9

ROCK
MOVING IN
A CIRCLE.



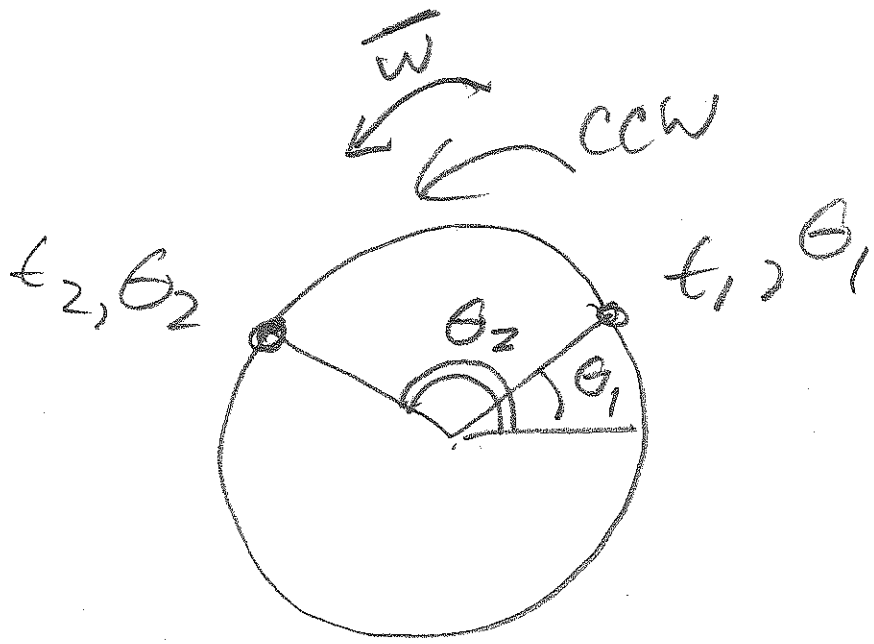
$s = r \cdot \theta$ H.S. geometry

$1 \text{ rad} = \frac{180 \text{ degrees}}{\pi}$

$30^\circ = \frac{30 \cdot \pi}{180} \text{ RAD} = \frac{\pi}{6} \text{ RAD}$

$45^\circ = \frac{45 \cdot \pi}{180} = \frac{\pi}{4} \text{ RAD}$

(3)



$$\bar{\omega} = \frac{\theta_2 - \theta_1}{t_2 - t_1} = \frac{\Delta\theta}{\Delta t} \left(\frac{\text{RAD}}{\text{s}} \right)$$



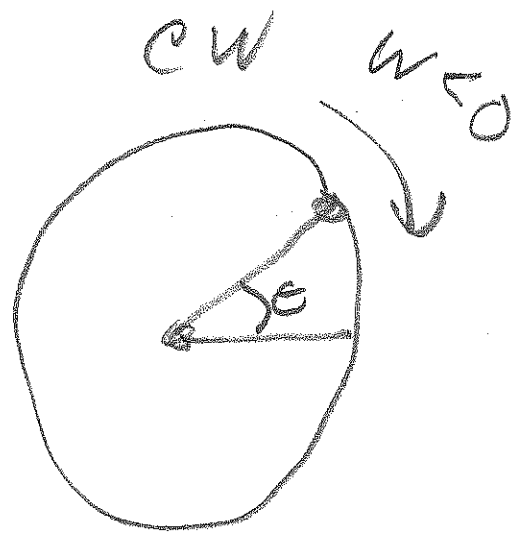
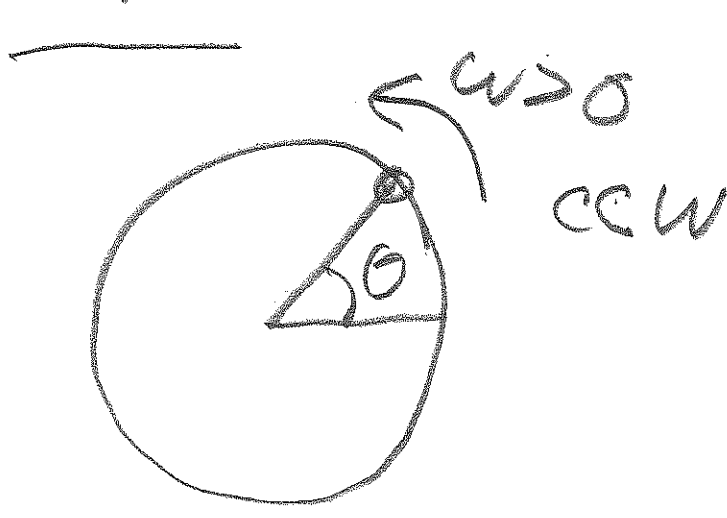
$$\omega = \lim_{\Delta t \rightarrow 0} \frac{\Delta\theta}{\Delta t}$$

instantaneous
angular
velocity $\left(\frac{\text{RAD}}{\text{s}} \right)$

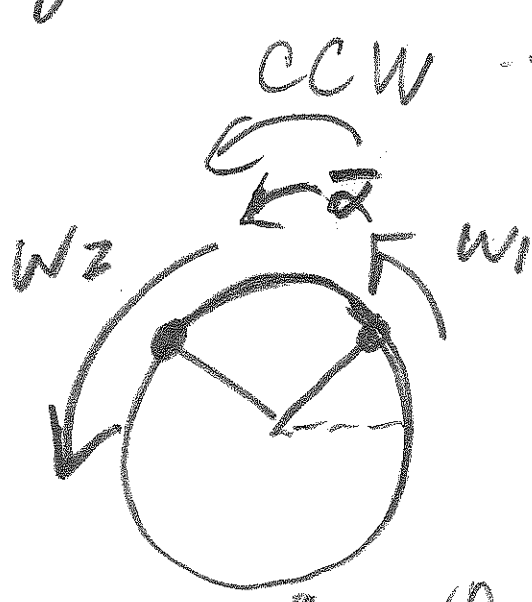
$\alpha = \text{ALPHA}$

$\omega = \text{omega not } W$

SIGNS:



angular acceleration (α)



$$\alpha = \frac{\omega_2 - \omega_1}{t_2 - t_1}$$

$$\alpha = \frac{\Delta \omega}{\Delta t}$$

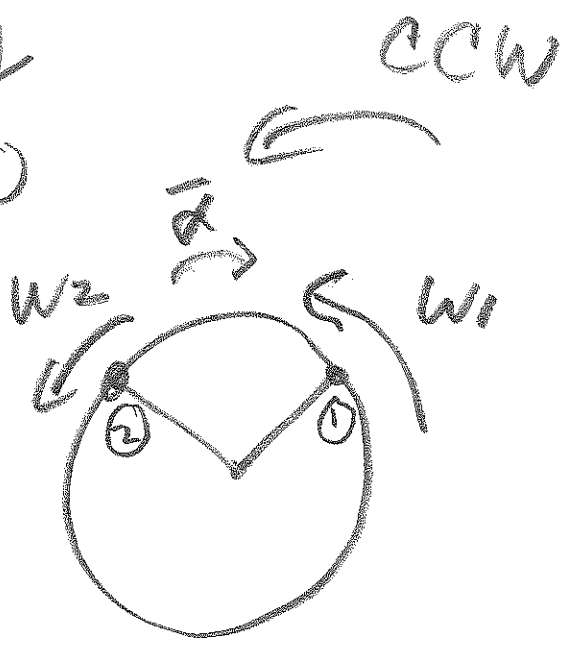
(RAD/S²)

NOTE:
 $\alpha > 0$
 IN THIS
 EXAMPLE

speeding up

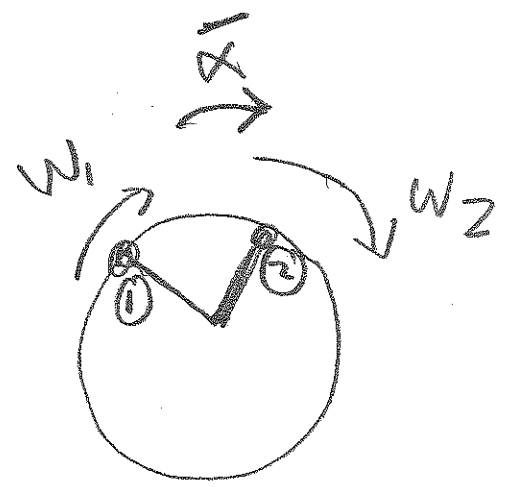
5

Examples of $\angle < 0$



$$\angle = \frac{w_2 - w_1}{t_2 - t_1} < 0$$

$$w_2 < w_1$$



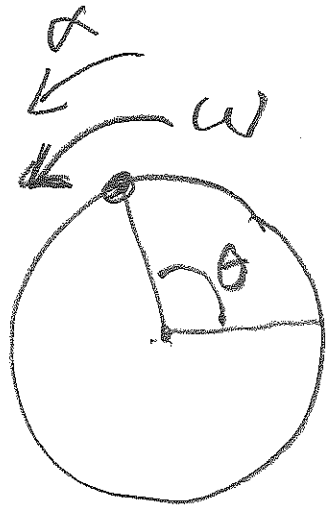
$$\angle = \frac{w_2 - w_1}{t_2 - t_1} < 0$$

$$w_2 < 0$$

$$w_1 < 0$$

$$|w_2| > |w_1|$$

(6)



$$\alpha = \lim_{\Delta t \rightarrow 0} \frac{\Delta \omega}{\Delta t}$$

$$[\theta = \text{theta}]$$

SPECIAL CASE: WHEN $\alpha = \text{constant}$

CH 2 \rightarrow X POS
 $a_x = \text{constant}$

$$v_2 = v_1 + a_x \cdot \Delta t$$

$$v_2^2 = v_1^2 + 2 \cdot a_x \cdot \Delta x$$

$$\Delta x = x_2 - x_1 = v_1 \cdot \Delta t + \frac{1}{2} a_x \Delta t^2$$

$$\bar{v} = \frac{v_1 + v_2}{2} \Rightarrow \Delta x = \bar{v} \cdot \Delta t$$

CH 9 $\alpha = \text{CONST.}$

(POS) \curvearrowright

$$\omega_2 = \omega_1 + \alpha \cdot \Delta t$$

$$\omega_2^2 = \omega_1^2 + 2\alpha \cdot \Delta \theta$$

$$\Delta \theta = \omega_1 \cdot \Delta t + \frac{1}{2} \alpha \Delta t^2$$

$$\bar{\omega} = \frac{\omega_1 + \omega_2}{2}$$

and $\Delta \theta = \bar{\omega} \cdot \Delta t$

Example 9.2

$$\alpha = 2.00 \frac{\text{RAD}}{\text{S}^2}$$

$$\omega_1 = 4.00 \frac{\text{RAD}}{\text{S}}$$

$$t_1 = 0$$

$$t_2 = 3.00 (\text{S})$$

$$\theta_1 = 0$$

$$\theta_2 = ?$$

$$\omega_2 = ?$$

$$\omega_2 = \omega_1 + \alpha \cdot \Delta t$$

$$\omega_2 = 4 + (2) \cdot (3)$$

$$\omega_2 = 4 + 6 = 10 \frac{\text{RAD}}{\text{S}}$$

OR

$$\omega_2^2 = \omega_1^2 + 2 \cdot \alpha \cdot \Delta \theta$$

$$\omega_2^2 = 4^2 + 2 \cdot 2 \cdot 21$$

$$16 + 4 \cdot 21 = 100$$

$$\omega_2 = 10 \frac{\text{RAD}}{\text{S}}$$

Test 3 Review

$$\Delta t = t_2 - t_1$$

$$\Delta \theta = \omega_1 \Delta t + \frac{1}{2} \alpha \cdot \Delta t^2$$

$$\theta_2 - \theta_1 = \omega_1 \cdot \Delta t + \frac{1}{2} \alpha \cdot \Delta t^2$$

$$\Delta \theta = 4 \cdot 3 + \frac{1}{2} \cdot 2 \cdot 3^2$$

$$\Delta \theta = 21 \text{ RADS} = \theta_2$$

($\theta_1 = 0$)

$$21 \cdot \frac{180}{\pi} = 1204^\circ$$

$$\frac{1204^\circ}{360^\circ} = 3.34 \text{ RATIO}$$

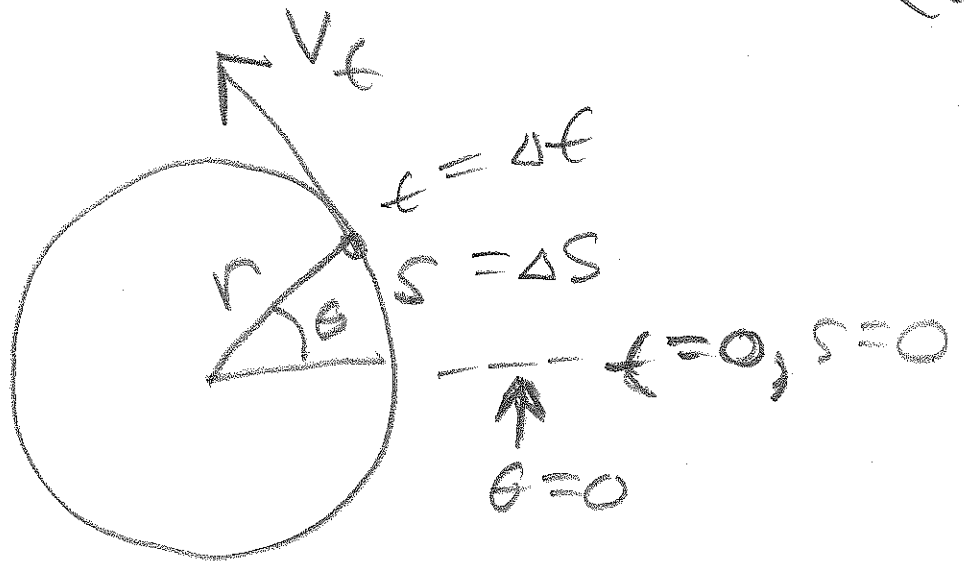
$$= 3 \text{ REV} + 0.34 \text{ REV}$$

$$(0.34)(360^\circ) = 122.4^\circ$$



sec 9.3

(8)

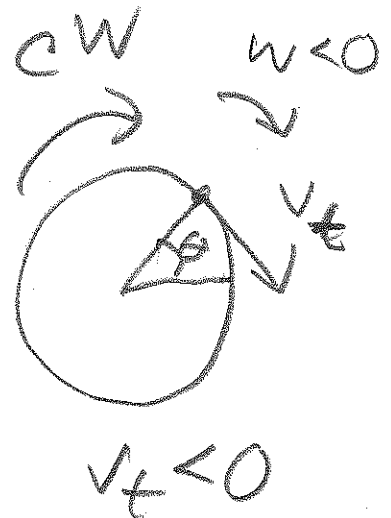
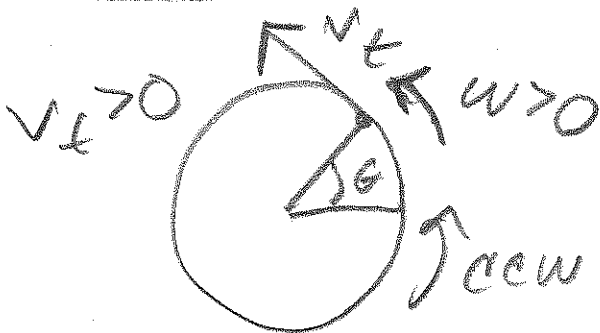


$$v_t = \lim_{\Delta t \rightarrow 0} \frac{\Delta s}{\Delta t}$$

$$v_t = \lim_{\Delta t \rightarrow 0} \frac{r \cdot \Delta \theta}{\Delta t}$$

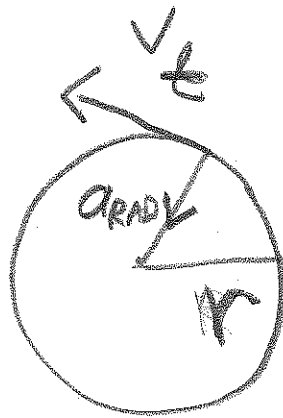
$$v_t = r \lim_{\Delta t \rightarrow 0} \frac{\Delta \theta}{\Delta t}$$

$$v_t = r \cdot \omega$$



sec 9.3

CN3



$|v_t| = \text{CONSTANT}$

UNIFORM
CIRCULAR
MOTION

$(\alpha = 0)$

$$a_{RAD} = \frac{v_t^2}{R}$$

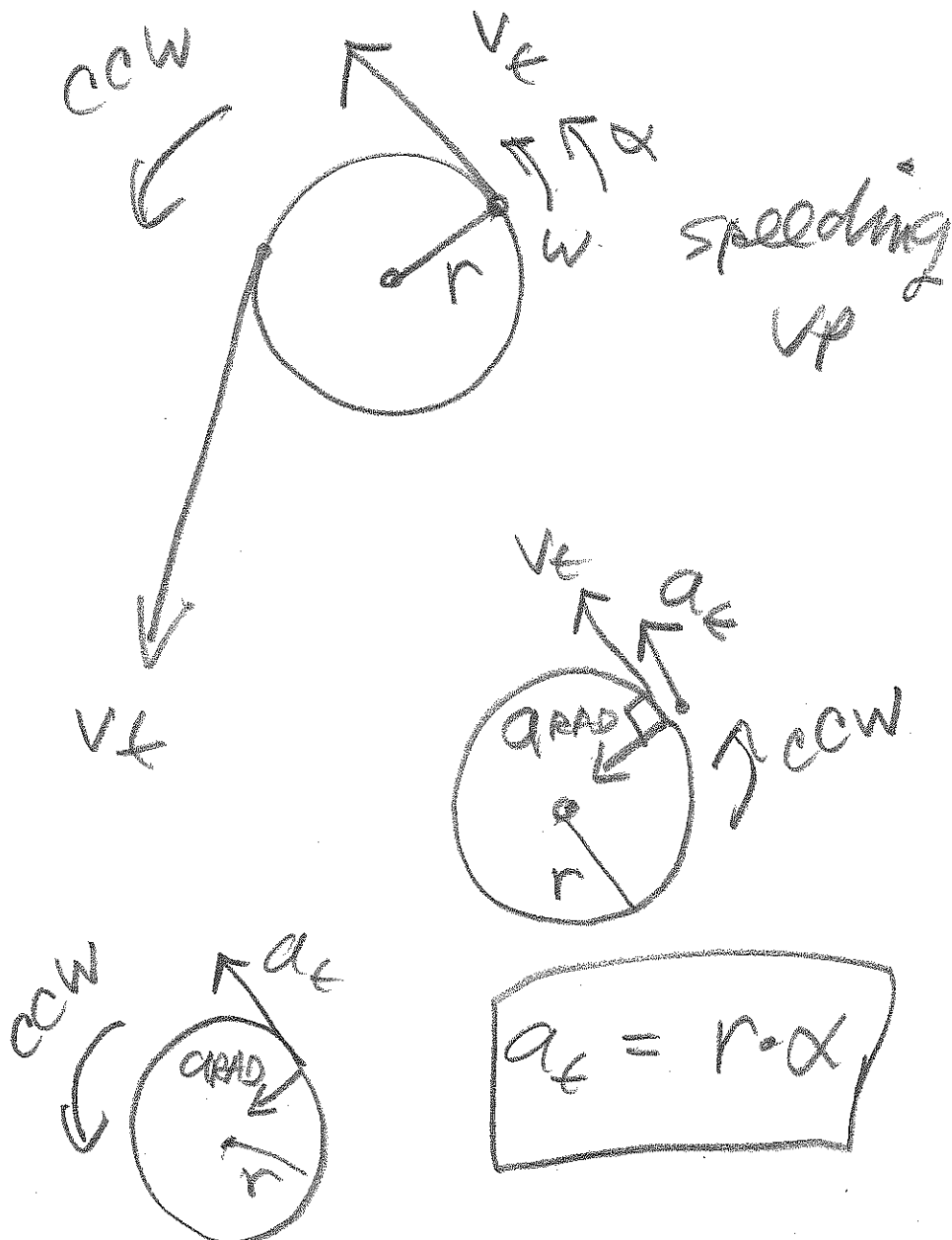
CN9

$$v_t = r \omega$$

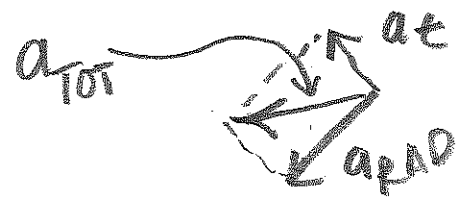
$$a_{RAD} = \frac{(r\omega)^2}{r}$$

$$a_{RAD} = \frac{r^2 \omega^2}{r}$$

$$a_{RAD} = r\omega^2$$



$$a_{TOT} = \sqrt{a_{RAD}^2 + a_t^2}$$



Sec. 9.4

Rotational KE.

SOLID CYLINDER
 ω AXIS

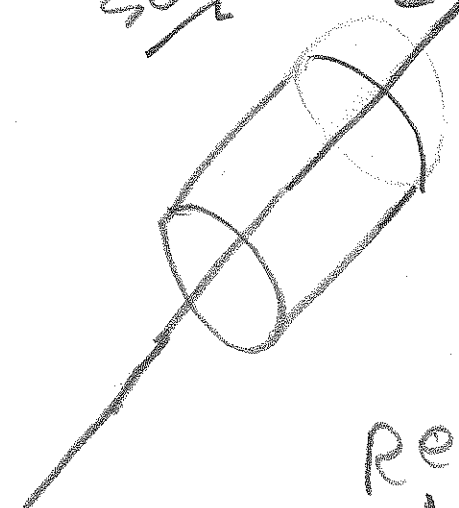
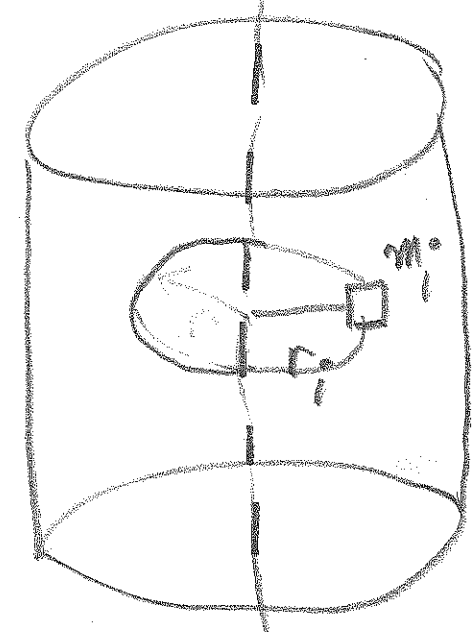


fig 9.2 (f)

re-align picture

ω

ABOUT 25
 6×10^{25}
 molecules
 in disk of
 Fe_0



$m_i = i$ th
 MOLECULE

$$KE_i = \frac{1}{2} m_i v_i^2$$

$$= \frac{1}{2} m_i r_i^2 \omega^2$$

$$KE_{TOT} = \sum_{i=1}^N \frac{1}{2} m_i r_i^2 \omega^2$$

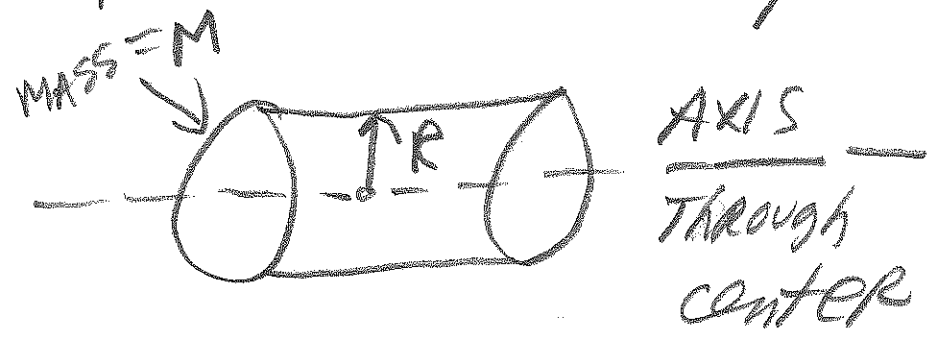
$$N \approx 6 \times 10^{25}$$

$$\sum_{i=1}^N \frac{1}{2} m_i r_i^2 \omega^2 = \frac{\omega^2}{2} \sum_{i=1}^N m_i r_i^2 = \frac{\omega^2}{2} I = \frac{1}{2} I \omega^2$$

$I =$ moment of inertia
 $=$ rotational inertia
of a solid disk

$$I = \sum_{i=1}^N m_i r_i^2$$

note: $I = \frac{1}{2} MR^2$
for solid disk



see table for various



SOLID SPHERE
 $I = \frac{2}{5} MR^2$